### **ROBOFORM 350/550**



Step into a dynamic manufacturing





Connectors: fibre-optic connector

Automotive connector

### Advanced technology

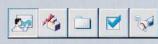
The ROBOFORM 350/550 series is exceptionally versatile since it delivers unequalled performance in a wide variety of applications: automotive, connectors, communication, medical, aeronautics, household appliances and many more.

The ROBOFORM 350/550 are the first to integrate Dynamic Process Control (DPControl), the new generation of numeric controls developed by CHARMILLES.

With a user interface dedicated to die-sinking, operators benefit from the unparalleled ease and efficiency of their working environment.



Preparation of job Job part 643871



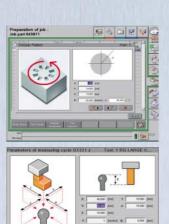
# Standard Windows platform:

- Integrated PC
- Touch screen
- Windows controlled
- CD-ROM, floppy drive
- Network

### A tailor-made interface

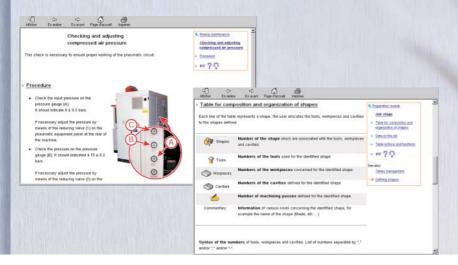
The new DPControl (Dynamic Process Control) interface has been developed, based on the findings of a survey conducted among mold-making professionals. The study was instrumental in designing interface functions and optimizing screen ergonomics. The user-friendliness of CHARMILLES interfaces – already a recognized standard in the industry – has been further enhanced to satisfy even more the stringent requirements of die-sinking professionals.

TO DE



### Interactive graphics

All operations such as measuring and machining cycles as well as cavity positioning are illustrated by graphics/icons designed to facilitate intuitive and spontaneous comprehension by the operator.

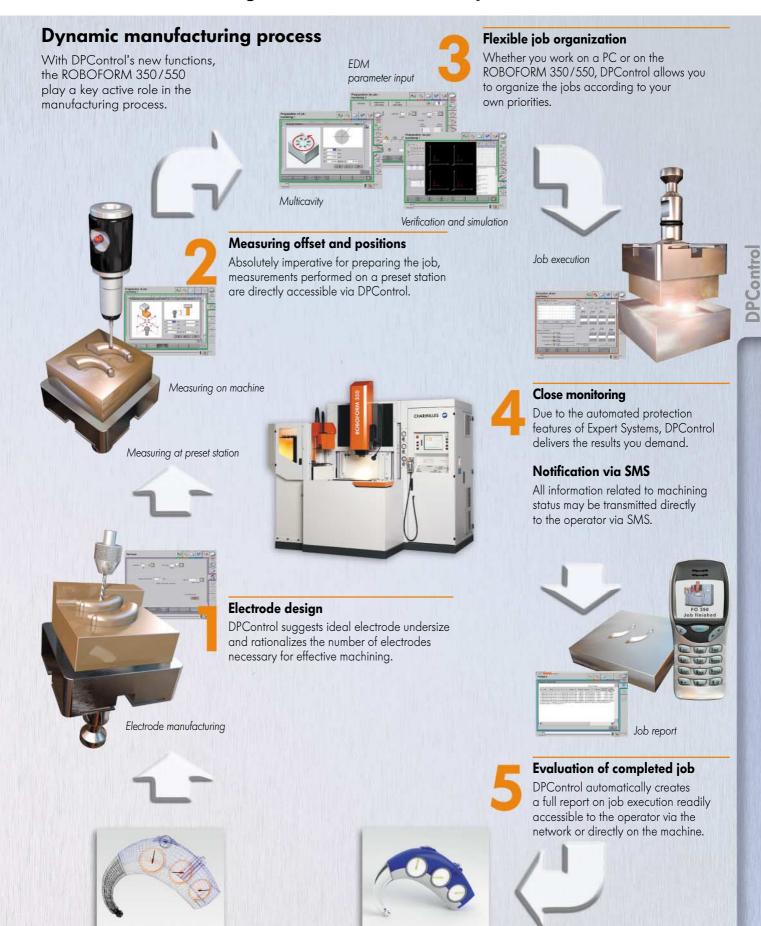


### Integrated e-documentation

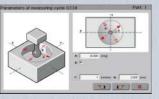
Large, cumbersome manuals are a thing of the past because they are now replaced by documentation in electronic format (HTML). When help is needed, the operator presses the F1 key on the keyboard to instantly receive easy-to-understand information about the current function.

**PControl** 

### DPControl, active integration into the workshop



### Interactive graphics programming



Measuring cycle

Machining cycle

### **Innovative set-up functions**

New automatic measuring cycles using high axis speeds considerably shorten job preparation time. What's more, DPControl communicates with a preset station, thus avoiding the need to enter values manually.

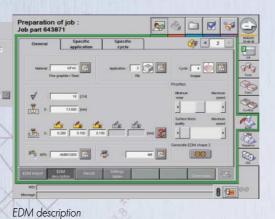


Electrode set-up

### **Optimum machining strategy**

DPControl offers clear choices for each application and generates the optimum machining strategy for top performance.

On just one screen the operator enters machining parameters such as surface finish, machining depth, machining cycle and type of application in order to obtain the best possible generator performance.





Orbit patterns

Sequence Assistant

### **Automated sequencing**

### Choose your priorities

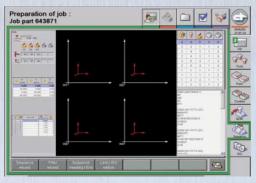
Based upon machining strategies, number of electrodes and workpieces, the Sequence screen automatically organizes successive machining phases.

If required, this can be modified according to criteria defined by the operator through the Sequence Assistant. Following validation, the ISO program is generated prior to machining.





Machining sequence



### Job simulation

.

# Detailed check by graphics simulation

This last phase prior to machining allows to visually verify on screen the proper sequencing. In other words, any verification by real axis movement is no longer needed. What's more, machining progress can be monitored during machining.



# Close monitoring With DPControl the oper overview of the evolution and of machining conditions.

With DPControl the operator has a precise overview of the evolution of output efficiency and of machining conditions. A multitude of functions are available such as graphics monitoring, visualization of current sequence as well as machining history.



Machining monitoring

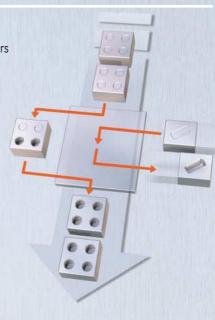
### Maximize productive time

To address this need, DPControl delivers unique solutions:

- Part Express: allows to interrupt the operation in progress in order to insert a more urgent job.
- Job List: organizes job sequence according to manufacturing priorities.



Job List



Part Express

Machining report

### Complete machining report

When job is completed, all details are described in reports listing, machining strategy, spark time, interruption, etc.

This information is most valuable in order to:

- Check completed jobs.
- Archive data.
- Expand know-how.
- Calculate production costs.



Job archiving





### **CHARMILLES Expert Systems: quality and performance**



### **PILOT-EXPERT 3**

# Around-the-clock monitoring and optimization

PILOT-EXPERT 3 guarantees top performance while taking into account machining conditions at all times.

It provides for unattended machining and delivers perfect job reproducibility.



# V

# POWER CONTROL EXPERT

### Mastering the spark

POWER CONTROL EXPERT checks

each spark to ensure a perfect quality of surface finish. It also allows to determine in real time the intensity of machining discharge as the electrode's surface increases.





### **SPAC®**

### A CHARMILLES exclusive

SPAC® allows to eliminate any short circuit by applying a specific discharge during a fraction of a second.

No longer slowed down due to short circuits, machining

continues at full speed and without interruption, thus improving productivity.

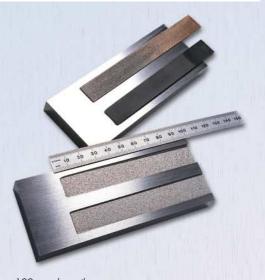




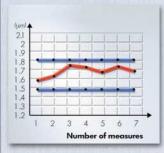
### Dovetail rib Material: Graphite/Steel Dimensions: 0.59 x 0.04 in Machining time: 1 h 06 min Technology: Rib

### Machining deep ribs

Due to increased axis speed and acceleration linked to PILOT-EXPERT 3, the ROBOFORM 350/550 reach exceptional performance. Without flushing and therefore without lateral deformation of the cavity, workpieces comply with the most stringent tolerances of geometry.



100 mm deep rib Dimensions: 0.59 x 0.08 in Without flushing Material: fine Graphite and copper/Steel Technology: Rib



Surface finish: CH 24/Ra 1.65 µm Average: 1.68, distortion: 2.1% Standard deviation: 3.4% Max. tolerance: ±10% Measurement outside tolerance: 0



### Surface finish quality

The uniformity of workpiece texture is directly linked to the quality of the mold surface. To obtain a perfect surface, CHARMILLES has developed Surface technology to satisfy the most stringent criteria of consistent surface finish.

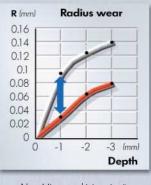
GPS mold Material: Graphite/Steel Dimensions: 19.4 in<sup>2</sup> Surface finish: CH 22/Ra 1.26 µm Technology: Surface



Mold for phone connector Material: Copper/Steel Surface finish: CH 22/Ra 1.26 µm Precision:  $\pm$  0.0002 in Technology: Micro-machining

### Micro Machining

When electrode dimensions are reduced in micro-machining, speed and wear become critical factors. CHARMILLES has developed a spark circuit capable of reducing machining time, lowering electrode wear by a factor of 3 while machining the surface



New Micro-machining circuit

Conventional

Factor of 3

### Mold subgates

Each mold has at least one injection point. This type of machining requires a 3D cycle and a strategy adapted to evolving electrode surfaces. The calculated geometric data necessary to describe the electrode movement is automatic, based on workshop drawings.



### Contouring

Contouring technology allows the use of cylindrical electrodes to accommodate complex geometries. These simple electrodes are easy to produce and reduce the cost of electrode manufacturing and optimizes flushing conditions and part straightness. Contouring widens the potential of die-sinking EDM.

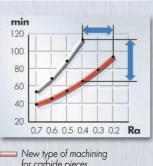




Material: Copper tungsten/Carbide Surface finish: CH 6/Ra 0.12 µm Precision: ± 0.0002 in Technology: Carbide

### **Quality and precision** for carbide machining

In-depth research has allowed CHARMILLES to develop a new generator module (K-HM). It has been developed to deliver unequalled performance in terms of surface finish and geometry. The results are simply spectacular: CH 6/Ra 0.2 µm, 40% of time savings and 50% less wear.



New type of machining for carbide pieces

■ Conventional

Time savings

Improved surface finish

# The Mechanical Design

### Precise, rugged and designed to last



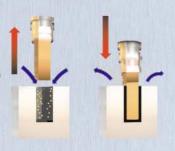
Short C frame

### Rugged mechanical design

A short oversized cast-iron C frame delivers mechanical stability and precision for the life of the machine – regardless of workpiece weight or dielectric volume. In addition, a rugged design absorbs all machining forces in order to maintain a precise gap between workpiece and electrode.



Large oversized ballscrews and linear guideways



High-speed pulse for complete particle removal

### High speed and acceleration

Based on studies conducted to define optimum values, CHARMILLES has multiplied pulse and acceleration speeds of the Z axis in order to improve particle removal in the spark gap cavities. This technology allows deep down machining without flushing and therefore without cavity deformation. This ballscrew technology not only delivers precision but it also provides job repeatability.



High-speed pulse in machining



# Fast, convenient workpiece set-up

Drop tank for easy access on two sides of the work area. In addition, the operator is able to program work tank level to accommodate workpiece height and therefore to facilitate automation. The fixed table prevents any risk of damage to the guides when loading heavy workpieces.

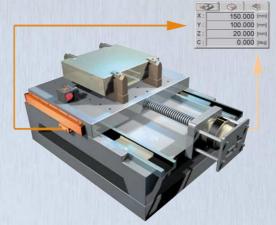
Easy access

### **Guaranteed quality**

# Linear glass scales for lifetime precision

To obtain lasting precision, only linear glass scales are truly effective. They eliminate all common errors caused by backlash, expansion and ballscrew wear.

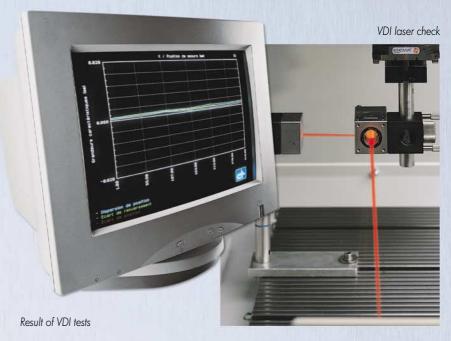
The Dual Loop Positioning System (DLPS) developed by CHARMILLES is a true closed-loop feedback solution designed to deliver high precision regardless of travel. It does away with the need for regular maintenance and calibration.



Linear glass scales for repeatable precision

### VDI axis positioning check

Before delivery, each machine is checked by laser to verify compliance of each axis movement with VDI 3441 standards (more than 150 positions checked per axis). These stringent standards include positional uncertainty, maximum positioning dispersion, positional deviation and maximum backlash.



### Ongoing quality assurance

At each step of the manufacturing process, our products' stringent inspections are conducted by qualified technicians.

Compliance protocols and signatures guarantee product quality and accountability.

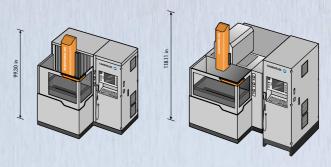


Assembly line

CHARMILLES 🚭

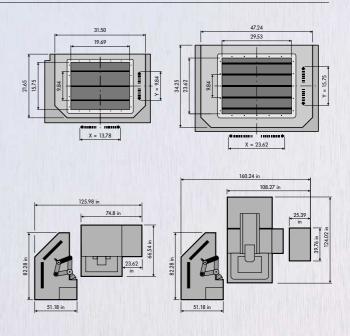
### **Technical specifications**

### **ROBOFORM 350/550**



	ROBOFORM 350	ROBOFORM 550
	Compact machine with fixed table	Short C frame, fixed table
in	74.80 x 66.54 x 99.29	108.27 x 124.02 x 118.11
lbs	6200	9700
Complies with "Machines, Safety and Health" directive		89/392/CEE
	89/336/CEE	89/336/CEE
in	13.78 x 9.84 x 11.81	23.62 x 15.75 x 17.72
	Linear glass scales	Linear glass scales
in	0.00004	0.000004
	Drop tank	Drop tank
in	31.50 x 21.65 x 14.57	48.08 x 34.25 x 18.50
in	3.94/12.80 programmable	5.71/17.32 programmable
in	19.69 x 15.75	29.53 x 23.62
in	0.47 (3)	0.47 (5)
lbs	110	220
lbs	1100	3530
in	30.71 x 20.87 x 11.81	47.24 x 33.46 x 15.75
in	5.91/17.72	5.91/23.62
	4 built-in paper cartridges	8 paper cartridges
gal	108	216
	in i	Compact machine with fixed table   in   74.80 x 66.54 x 99.29   lbs   6200   89/392/CEE   89/336/CEE     89/336/CEE

<sup>\*</sup> Width x depth x height



ROBOFORM 350QCRi.2 ROBOFORM 550QCRi.2

14

<sup>\*\*</sup> Width x depth

<sup>\*\*\*</sup> Optional

# **Technical specifications**

### **ROBOFORM 350/550**

Modules			ROBOFORM 350	ROBOFORM 550	
C axis (***)	Max. electrode inertia	lbs x in <sup>2</sup>	68	3	
	Measurement resolution °		0.001		
a la la deserva	Electrode weight	lbs		55	
pindle chuck (***)	System 3R			Macro/Combi	
	Mecatool Erowa			GPS70 ITS/ITS-Compact	
	Hirschmann		H8.1		
ool changer (***)	Linear (standard tooling)		4 pos./2.95 x 16.73 in	6 pos./2.76 x 16.73 in	
	Linear (Combi tooling)		5 pos./2.36 x 16.73 in	6 pos./2.36 x 16.73 in	
	Rotary (standard tooling)		16 pos./2.9		
	Rotary (Combi tooling		32 pos./1.4	2 x 9.84 in	
Aulticavity flushing (***)			6 out	puts	
additional power module		A		64	
dapter kit for external ro	obot		Optio		
C-HM			Optio		
e-ConnecT Programming system on F	PC		Optio		
Autorestart	C		Standard Standard		
HS-EDM			Stand		
			Oldino		
Power supply					
hree-phase input voltag		V	40		
Nain network frequency		Hz	50 o	r 60	
Generator					
ype			ISOPI	JISE	
Standard machining curr	ent	A	64		
PILOT-EXPERT 2 and 3:	Optimization and automatic ma	* * * * * * * * * * * * * * * * * * * *			
POWER CONTROL EXPE	ERT: Machining current, self-adaptin				
MICRO-MACHINING:	Monitors electrode wear in app				
SPAC®:	Protection against short circuits	(CT patent)	Stand	dard	
Numerical contro	,				
Architecture			PC multipi	2022207	
Operating system			Wind		
Processor			Penti		
Screen			LCD 12	2" TFT	
Data input			Touch screen		
Keyboard			PC-style alphanu		
Remote control			Stand		
Hard drive			10 (		
				IVID	
				lard	
CD-ROM drive	145 Parallel RS 232C Series (with V	Vindows standards)	Stand		
CD-ROM drive PCMCIA Port, Ethernet RJ	145, Parallel, RS 232C Series (with V	Vindows standards)			
CD-ROM drive PCMCIA Port, Ethernet RJ  DPControl function	ons	Vindows standards)	Stand		
CD-ROM drive PCMCIA Port, Ethernet RJ DPControl function D-JOB (Direct-Job) for ma	ons achining simple jobs	Vindows standards)	Stand		
CD-ROM drive CMCIA Port, Ethernet RJ DPControl function D-JOB (Direct-Job) for months of the properties of the propertie	ons achining simple jobs stant for simpler data input		Stand		
CD-ROM drive CMCIA Port, Ethernet RJ DPControl function D-JOB (Direct-Job) for monteractive graphics assistants Automatic measurement of	ons achining simple jobs stant for simpler data input cycles for workpieces and electrode		Stand		
CD-ROM drive CMCIA Port, Ethernet RJ DPControl function D-JOB (Direct-Job) for monteractive graphics assistant and the masurement of the monteractive masurement of the monteraction of measurement of the monteraction of the monterac	ons achining simple jobs stant for simpler data input cycles for workpieces and electrode ent results from preset station		Stand		
CD-ROM drive CMCIA Port, Ethernet RJ DPControl function D-JOB (Direct-Job) for monteractive graphics assist Automatic measurement of machining cycles with	chining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station in geometrical pattern		Stand		
CD-ROM drive CMCIA Port, Ethernet RJ CMCIA PORT, Ether	chining simple jobs stant for simpler data input cycles for workpieces and electrode ent results from preset station in geometrical pattern ill combinations of materials		Stand		
CD-ROM drive CMCIA Port, Ethernet RJ DPControl function D-JOB (Direct-Job) for monteractive graphics assist Automatic measurement of machining cycles with Machining strategy for a Dedicated technologies	chining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station in geometrical pattern		Stand		
CD-ROM drive CMCIA Port, Ethernet RJ CMCIA Port, Ether	cachining simple jobs stant for simpler data input cycles for workpieces and electrode ent results from preset station in geometrical pattern ill combinations of materials for each type of application and number of electrodes assistant according to manufacturing	25	Stand		
CD-ROM drive CMCIA Port, Ethernet RJ CMCIA Port, Ethernet RJ CD-JOB (Direct-Job) for monteractive graphics assist Automatic measurem in mportation of measurem in Machining strategy for a Dedicated technologies and to define undersize a Machining sequencing a Graphic machining simul	cons  achining simple jobs  stant for simpler data input cycles for workpieces and electrode ent results from preset station in geometrical pattern  all combinations of materials for each type of application and number of electrodes assistant according to manufacturing	25	Stand		
CD-ROM drive CMCIA Port, Ethernet RJ CPCONTrol functic CJOB (Direct-Job) for monteractive graphics assistant and the measurement of measurement of measurement of machining cycles with Machining strategy for a dedicated technologies and to define undersize a Machining sequencing a Graphic machining simul Machining report for each	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station in geometrical pattern all combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution	25	Stand		
CD-ROM drive CMCIA Port, Ethernet RJ CPCONTrol functic D-JOB (Direct-Job) for mo interactive graphics assis automatic measurement of inportation of measurem D machining cycles with Aachining strategy for a Dedicated technologies of id to define undersize a Achining sequencing a Draphic machining simul Aachining report for each ob List – Management of	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station in geometrical pattern ill combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution of pending jobs by order of priority	25	Stand		
D-ROM drive CMCIA Port, Ethernet RJ DPControl function DPControl function DPControl function DPControl function DPCONTROL for management of the control function of measurement of the control function of the con	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station in geometrical pattern all combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs	25	Stand		
CD-ROM drive CMCIA Port, Ethernet RJ DPControl function DJOB (Direct-Job) for monteractive graphics assist automatic measurement of measureme	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station negeometrical pattern all combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs whice explanations	priorities	Stand		
CD-ROM drive CMCIA Port, Ethernet RJ CMCIA Port, Ethernet RJ CD-JOB (Direct-Job) for monteractive graphics assist Automatic measurement of me	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station in geometrical pattern all combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs	priorities	Stand		
D-ROM drive CMCIA Port, Ethernet RJ DPControl functic D-JOB (Direct-Job) for monteractive graphics assist automatic measurement of machining strategy for a Dedicated technologies and to define undersize a Machining sequencing a Graphic machining simul Machining report for each ob List – Management of art Express – Instant insecontextual aid with grap mbedded documentation.	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station negeometrical pattern all combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs whice explanations	priorities	Stand		
CD-ROM drive CMCIA Port, Ethernet RJ CMCIA Port, Ether	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station negeometrical pattern all combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs whice explanations	priorities	Stand	Jard	
CD-ROM drive CMCIA Port, Ethernet RJ CMCIA Port, Ethernet RJ CD-JOB (Direct-Job) for monteractive graphics assist Automatic measurement of me	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station negeometrical pattern all combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs whice explanations	priorities  in lbs	\$1.18 x 82.20	28 x 97.64 50	
CD-ROM drive CMCIA Port, Ethernet RJ CMCIA PORT, Ether	achining simple jobs stant for simpler data input cycles for workpieces and electrode tent results from preset station negeometrical pattern all combinations of materials for each type of application and number of electrodes assistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs whice explanations	priorities  in lbs lbs	\$1.18 x 82.:  20: 44	28 x 97.64 50	
CD-ROM drive PCMCIA Port, Ethernet RJ PCMCIA Port, Ethernet RJ DPControl functic D-JOB (Direct-Job) for monteractive graphics assis Automatic measurement of	achining simple jobs stant for simpler data input cycles for workpieces and electrode eitent results from preset station in geometrical pattern ill combinations of materials for each type of application and number of electrodes essistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs whice explanations on le-docl on the use of the machine	priorities  in lbs	\$1.18 x 82.1 200 44	28 x 97.64 50 4	
DPControl function D-JOB (Direct-Job) for monteractive graphics assists Automatic measurement of	achining simple jobs stant for simpler data input cycles for workpieces and electrode eitent results from preset station in geometrical pattern ill combinations of materials for each type of application and number of electrodes essistant according to manufacturing lation ch job execution of pending jobs by order of priority ertion of urgent jobs whice explanations on le-docl on the use of the machine	priorities  in lbs lbs	\$1.18 x 82.:  20: 44	28 x 97.64 50 4 0 (8; 90/4	

CHARMILLES ©

